BALANCING COORDINATION MECHANISMS IN COMPLEX PRODUCT SYSTEMS DEVELOPMENT – A CASE STUDY OF AN EUROPEAN R&D COLLABORATION

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Complex Product Systems - CoPS

CoPS vs. mass production industries (two ideal types)

	CoPs project organisation	Commodity products, functional organisation ^a		
Product characteristics	Complex component interfaces High unit cost Product cycles last decades Many skill/knowledge inputs (Many) tailored components	Simple interfaces Low unit cost Short product life cycles Fewer skill/knowledge inputs Standardised components		
Production characteristics	Project/small batch Systems integration	High volume, large batch Design for manufacture		
Innovation processes	Innovation paths agreed ex-ante among suppliers, users etc.	Innovation path mediated by market selection		
	People-embodied knowledge	Machinery embodied knowhow		
Competitive strategies and	Focus on product design and development	Focus on economies of scale/cost minimisation		
innovation coordination	Organic	Mechanistic		
	Systems integration competencies	Volume production competencies		
	Management of multi-firm alliances in temporary	Focus on single firm (e.g., lean production,		
	projects	TQM,MRP II)		
Industrial coordination and evolution	Elaborate networks	Large firm/supply chain structure		
	Project-based multi-firm alliances	Single firm as mass producer		
	Temporary multi-firm alliances for innovation and production	Alliances usually for R & D or asset exchange		
	Long-term stability at integrator level	Dominant design signals industry shakeout		
		Hobday, 1998		



Knowledge Integration

"an efficient knowledge integration occurs when organizations maximize the use of impersonal mechanisms, and leave the costly and more personal mechanisms for group problem solving and decision making, the last taking the form of meetings" (Grant, 1996).





Literature Gap

- How does the use of personal and impersonal coordination evolve throughout the phases of a CoPS project?
- How are personal and impersonal coordination mechanisms combined and balanced?



Methodology

- * Single case study
- * MIDCAS project as the unit of analysis
- 12 interviews, study visits in Saab, extensive documentation public (midcas.org)



MIDCAS: An incremental and Iterative Development





MIDCAS: An incremental and Iterative Development

	1 st phase: defining requirements and solution	2 nd phase: Implementing solution				
S&A Function Design	1 st Increment	2 nd Increment	3 rd Increment	4 th Increment	5 th Increment	
S&A simulation	Development of the simulator	1 st Increment	2 nd Increment	3 rd Increment	4 th Increment	
S&A manned demonstrator	Sensor flight tests		1 st Increment	2 nd Increment		
S&A unmanned demonstrator					1 st Increment	2 nd Increment
Standardization workshops with stakeholders	1 st Standardization workshop	2 nd Standardizatio n workshop	3 rd Standardizatio n workshop	4 th Standardizatio n workshop	5 th Standardizatio n workshop	6 th Standardizati on workshop



Evolution of Coordination Modes

	1 st phase: Defining requirements and solutions	2 nd Phase: Implementing solutions				
Project Context	Project with a high level of complexity and tas	oject with a high level of complexity and task interdependence / coopetitive context under knowledge protection and IPR				
Project Stage	Conceptual development and ideation	Development of demonstrators requiring more group problem solving; Refinement of requiring more group problem solving; specifications and requirements;Development of demonstrators Development of specifications;				
Status of project definition	Extensive statements of work; Solutions still loosely defined; Technical requirements and specifications still immature	Technical requirements and specifications maturing; Simulations results and manned demonstrator tests revealed some issues that needed to resolved	Technical requirements and specifications refined based on unmanned demonstrator tests and stakeholders feedback; S&A Function fully described			
Relational context and perceived understanding of the task	Their specific capabilities and competences are still rather unknown and trust is not yet developed.	Early implementation in simulation and demonstrator reveals diverse orientations of partners. A consensus-based decision model delays problem-solving.	Agreement on strengthening the decision-making model. Focus on completion of the project.			
Impersonal coordination mechanisms	The contract, statement of work, management model, released documents, designs, and standardized reports.	Gradually evolving as more document and specifications are developed in detail. Simulations and implementation in manned demonstrator outcomes represent a leap in accumulated codified material	Gradually evolving as more documents and specifications are developed in detail. Implementation in unmanned demonstrator outcomes represent a leap in accumulated codified material			
Electronic media	E-mails, skype meetings and telephone and video conferences	E-mails, skype meetings and telephone and video conferences	E-mails, skype meetings and telephone and video conferences			
Personal face-to- face coordination mechanisms	Sparse meetings between key managers / 1 st Standardization workshop	Extended workshops / Decision making meetings / Standardization workshops	Decrease of frequency of extended workshops and decision making meetings / Standardization workshops			



Implications

The balance between the mechanisms are affected by an evolving mutual understanding of the task as a consequence of:

- differences in partners orientation as integrators or suppliers.
- the early identification of problem areas based on the incremental approach and,
- the size of the codified knowledge base of the group,



Thank You

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