



# Amplitude and Phase Imbalance Calibration for Space-Based Precision Direction Finding Systems

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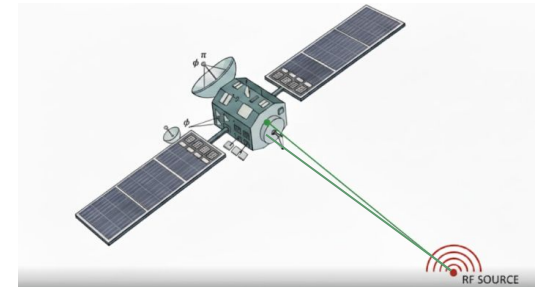
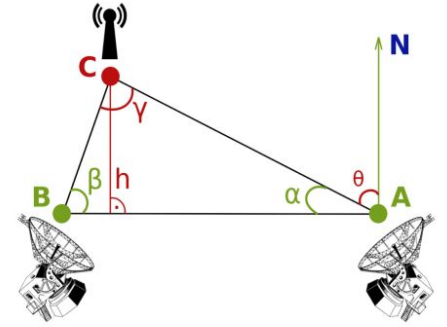
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# Outline

- Introduction
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- X-Band Dual-Channel RF Receiver System
- Offline and Online Calibration
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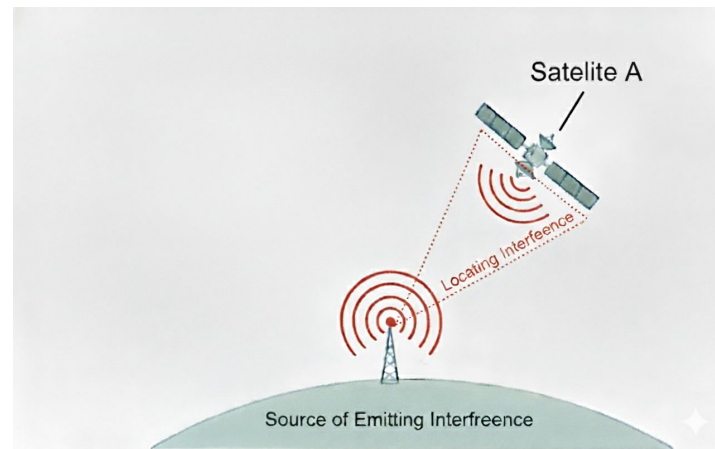
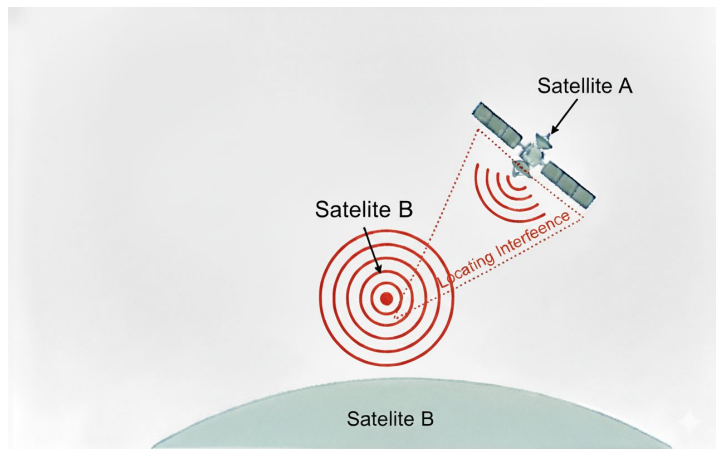
# Introduction

- Direction Finding - DF;
- Uses Triangulation and other techniques to find the location of radio sources;
- One of the most used solution is based on using two receiving antennas;
- Very used in radio navigation for ships, aircraft, search and rescue (emergency transmitters), **space systems**, illegal interference and etc.



# Introduction

- DF application in earth orbit.



# Introduction

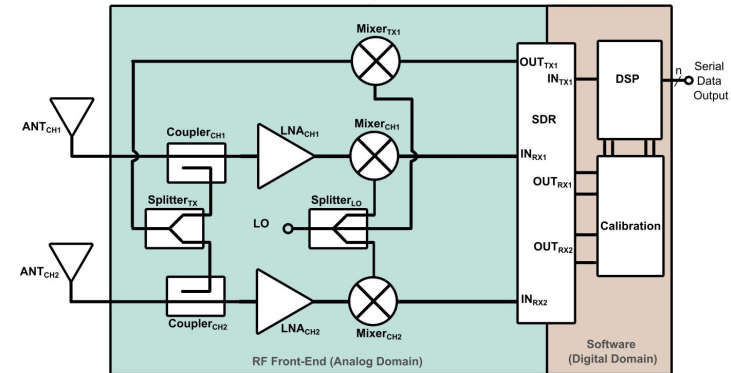
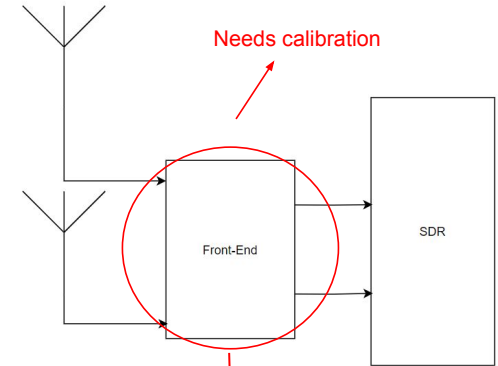
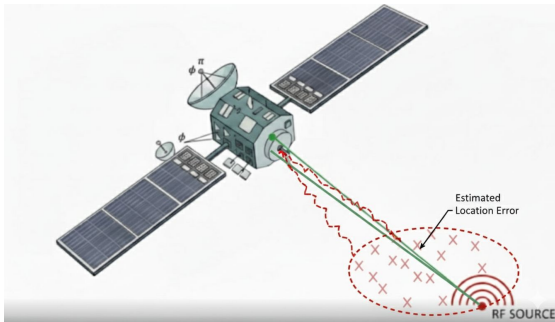
The front-end is used to properly conditioning the signal for a Software defined Radio (SDR).

Its calibration is necessary due to:

- Electrical and physical length variability;
- Active device variability as gain and time degradation;
- Temperature.

} **Dynamical Variability**

If not calibrated it introduces error in the DF algorithm due to channel imbalance.

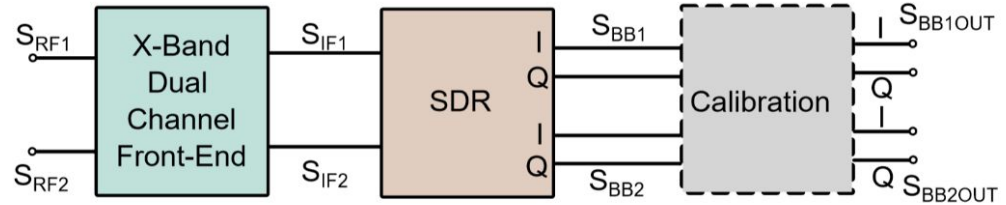


# Objective

- To apply the calibration technique in a real system;
- To discuss calibration for low cost learning SDRs like ADALM PLUTO;
- To Propose and compare online and offline calibration.

# Calibration System Description

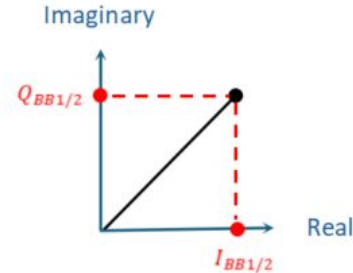
- RF Receiver Block at X-Band
- 8.5 to 9.5 GHz



$$S_{BB1/2} = I_{BB1/2} + jQ_{BB1/2} = |A_{BB1/2}| \angle \phi_{BB1/2}$$

$$|A_{BB1}| = \sqrt{I_{BB1/2}^2 + Q_{BB1/2}^2}$$

$$\phi_{BB1/2} = \tan^{-1} \left( \frac{Q_{BB1/2}}{I_{BB1/2}} \right)$$



# Calibration System Description

- Calibration methodology

$$\alpha_{BB12} = \frac{|A_{BB1}|}{|A_{BB2}|}$$

Amplitude Compensation

$$\Delta\phi_{BB12} = \phi_{BB1} - \phi_{BB2}$$

Phase Compensation

$$S_{BB1}^* = |A_{BB1}| e^{j(\phi_{BB1})} \quad \text{CH1}$$

$$S_{BB2}^* = \alpha_{BB12} |A_{BB2}| e^{j(\phi_{BB2} + \Delta\phi_{BB12})} \quad \text{CH2}$$

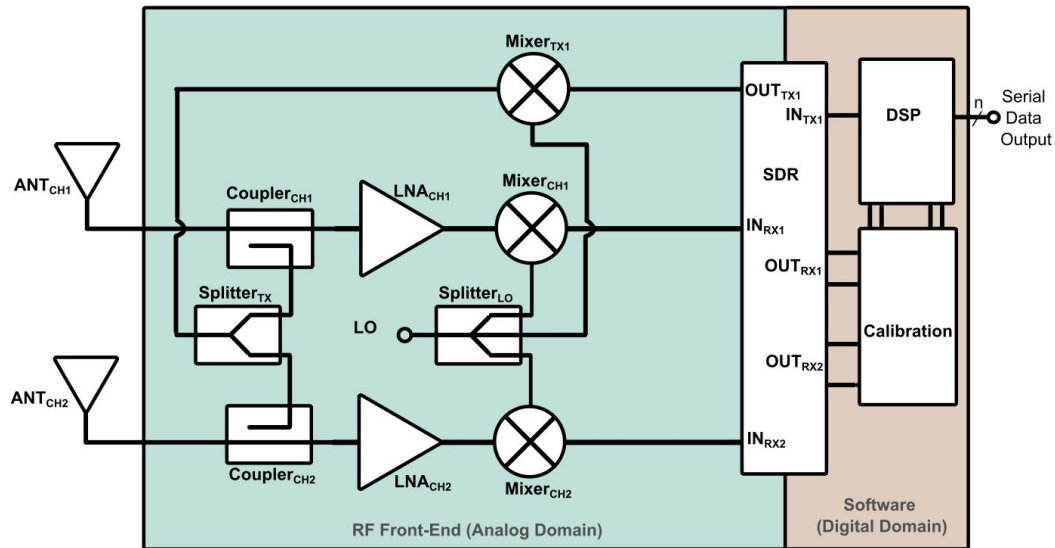
Calibrated Signal

$$S_{BB1}^* = |A_{BB1}| \angle\phi_{BB1} \quad \text{Reference Channel}$$

$$S_{BB2}^* = |\alpha_{BB12}| \angle\Delta\phi_{BB12} |A_{BB2}| \angle\phi_{BB2} = \alpha_{BB12} |A_{BB2}| \angle\phi_{BB2} + \Delta\phi_{BB12} = \frac{|A_{BB1}|}{|A_{BB2}|} |A_{BB2}| \angle\phi_{BB2} + \phi_{BB1} - \phi_{BB2} = |A_{BB1}| \angle\phi_{BB1}$$

# Calibration System Description

Proof of concept: X-band Front-end Local oscillator



Gain: 24 dB  
NF: 0.8 dB

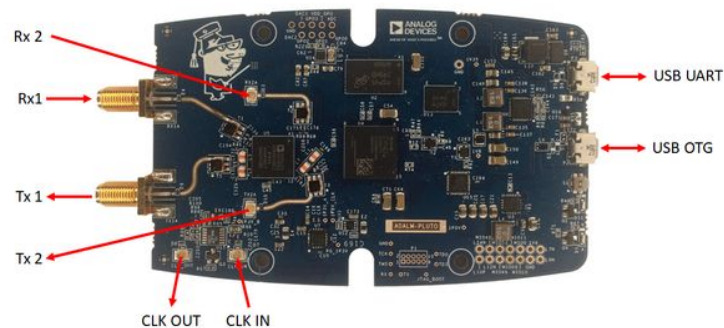
# Calibration System Description

## SDR

- ADALM-PLUTO (Revision C) - RF learning module;
- Based on the Analog Devices AD9363 - RF Agile Transceiver;
- 12-bit ADC and DAC;
- 15.72MS/s for two channel operation;
- RF coverage from 325 MHz to 3.8 GHz.

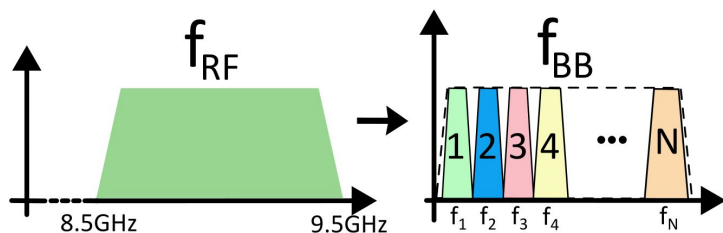


REF: [Adalm Pluto - Overview](#)



# Calibration System Description

- The SDR is not able to receive all the signal bandwidth (8.5 to 9.5 GHz implies 1 GHz bandwidth) at once.
- So the bandwidth will be split in N time multiplexed narrow-band channels according to the SDR limitations.
- IF bandwidth of 200 MHz (400 MHz up to 600 MHz)
- A baseband of 10 MHz was assumed so the RF receiving system should select 100 channels to accommodate the 1 GHz RF bandwidth.



$$\begin{bmatrix} |S_{BB2_1}^*| \\ |S_{BB2_2}^*| \\ \dots \\ |S_{BB2_n}^*| \end{bmatrix} = [\alpha_{BB2_1}] \cdot \begin{bmatrix} |A_{BB2_1}| \\ |A_{BB2_2}| \\ \dots \\ |A_{BB2_n}| \end{bmatrix}$$

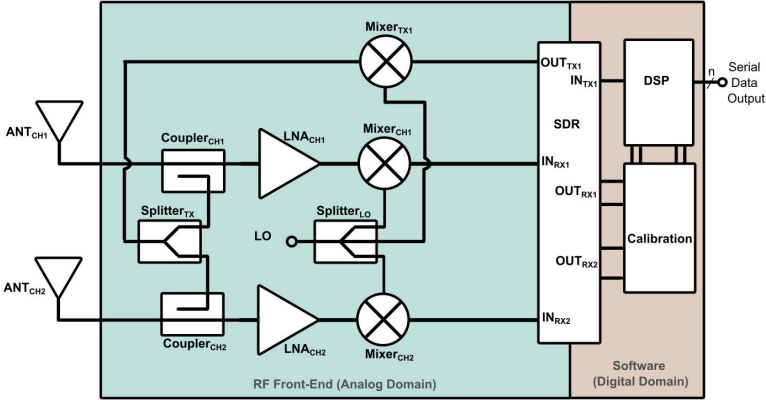
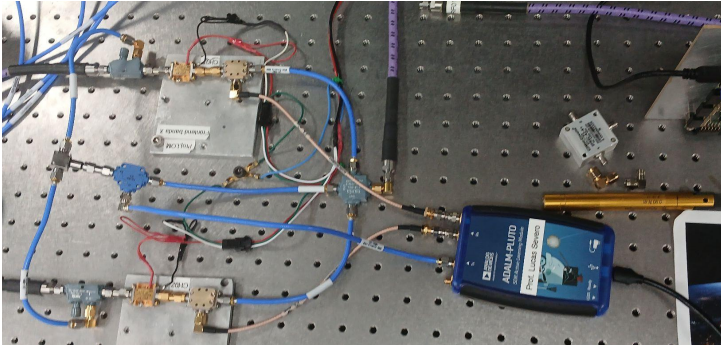
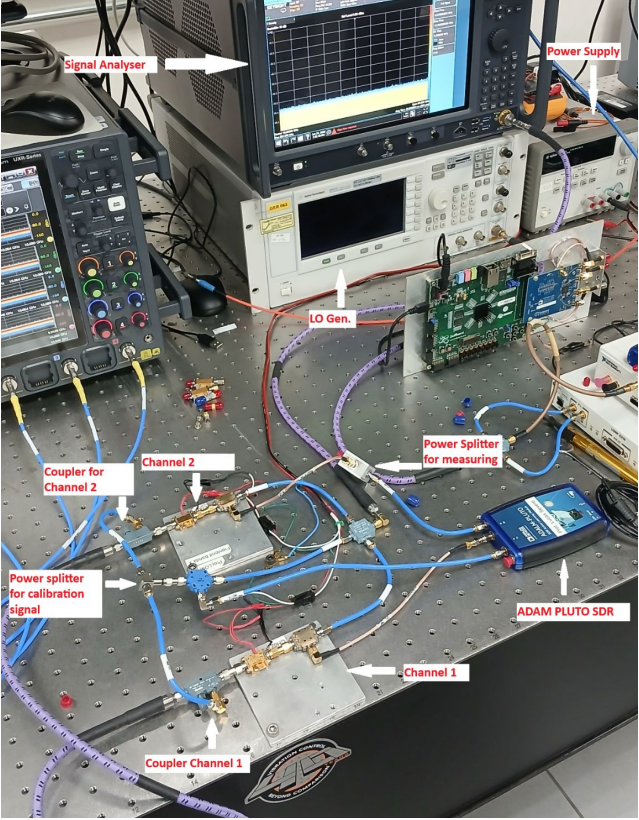
$$\begin{bmatrix} \phi_{BB2_1}^* \\ \phi_{BB2_2}^* \\ \dots \\ \phi_{BB2_n}^* \end{bmatrix} = [\phi_{BB2_1}] + \begin{bmatrix} \Delta\phi_{BB12_1} \\ \Delta\phi_{BB12_2} \\ \dots \\ \Delta\phi_{BB12_n} \end{bmatrix}$$

LO Frequency (GHz)	RF bandwidth (GHz)
8.1	8.5 - 8.7
8.3	8.7 - 8.9
8.5	8.9 - 9.1
8.7	9.1 - 9.3
8.9	9.3 - 9.5

IF bandwidth of 200 MHz (400 MHz up to 600 MHz) - ADALM PLUTO

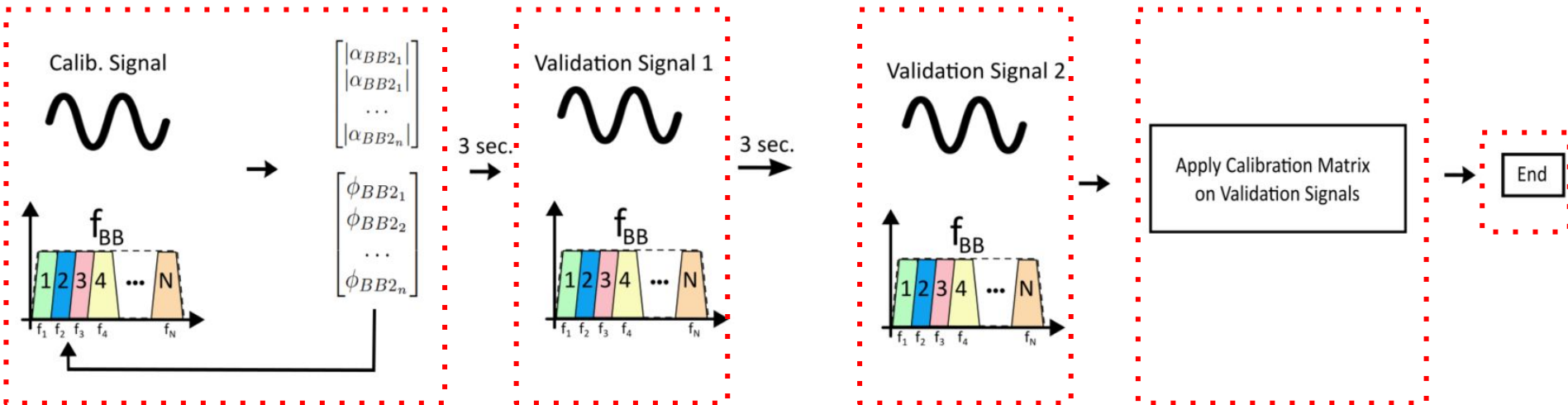
# Experimental Results

## Laboratorial Setup



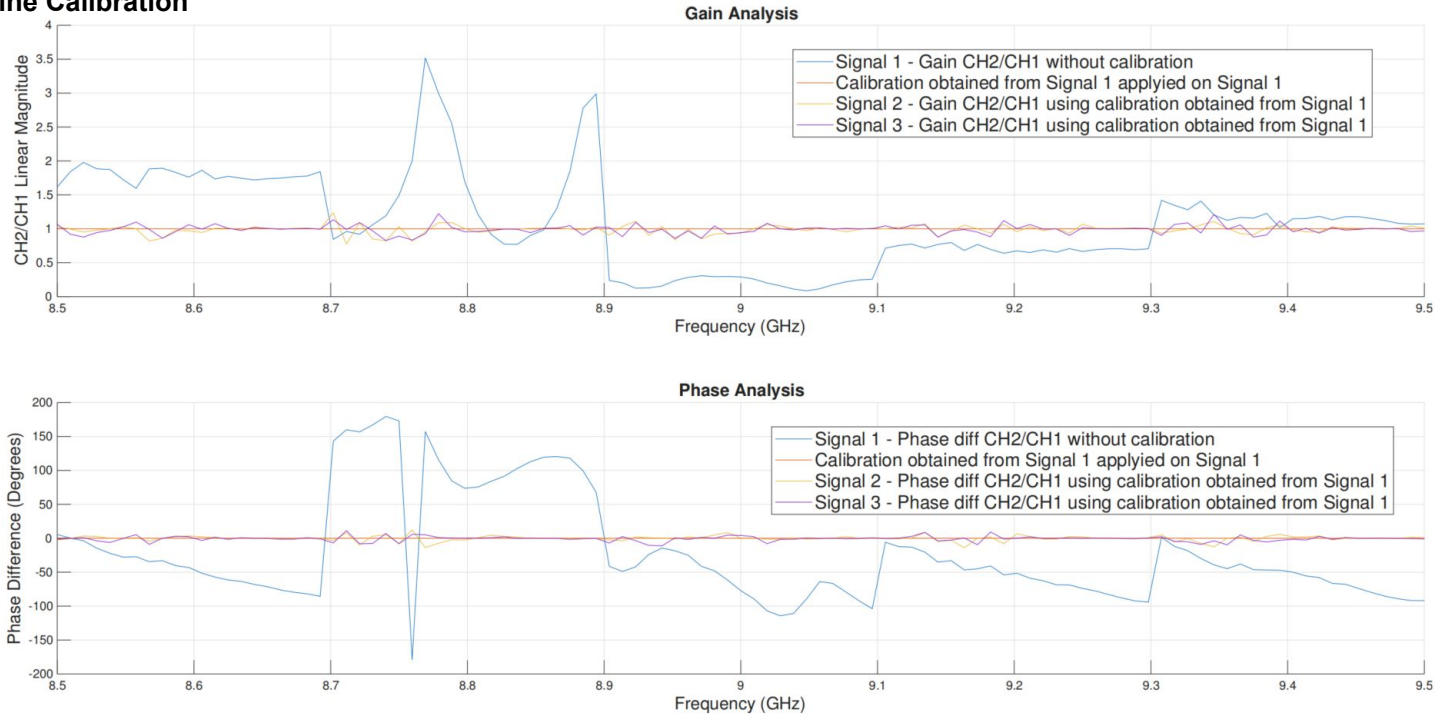
# Experimental Results

- Offline Calibration



# Experimental Results

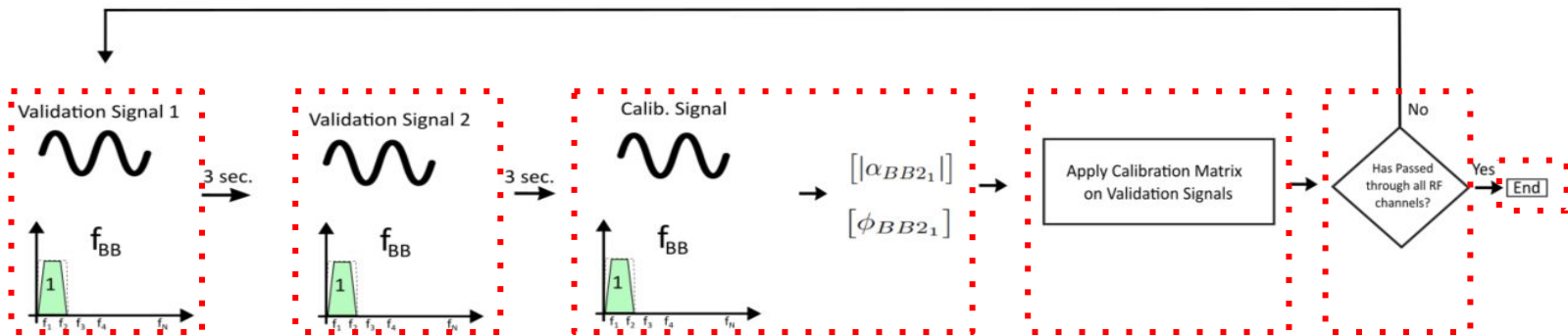
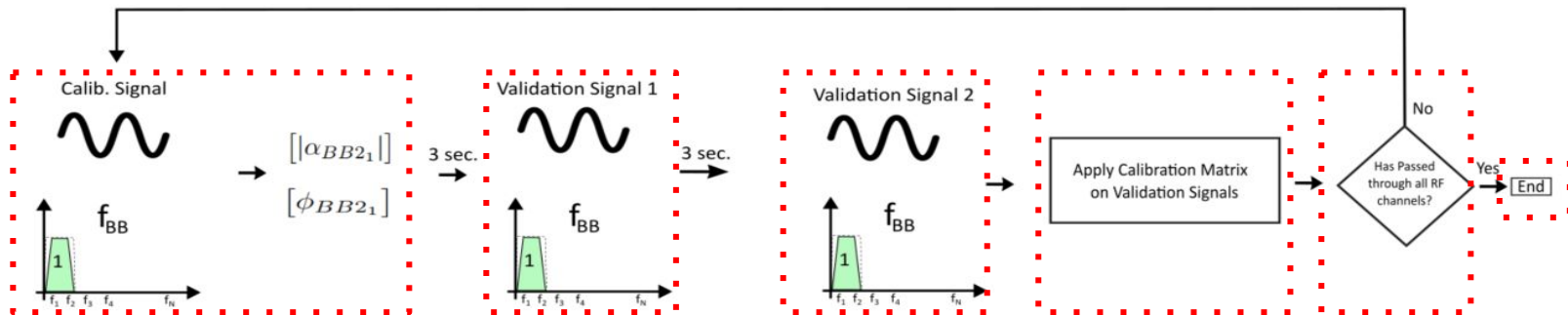
- Offline Calibration



However, the ADALM-PLUTO radio has demonstrated a lack of repeatability when the frequency of the internal LO is changed, so this calibration has led to some errors.

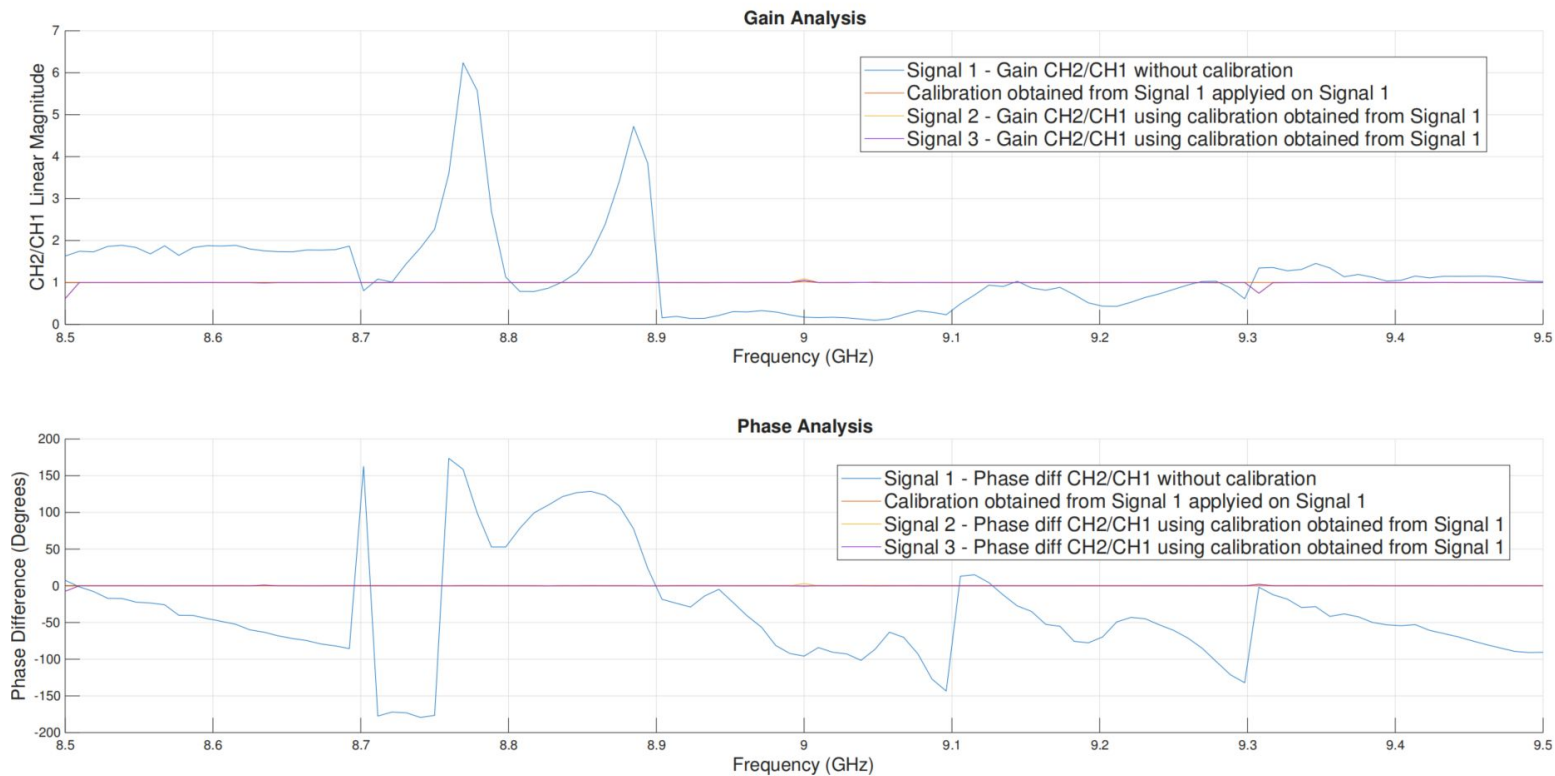
# Experimental Results

## Proposed method - Real Time Calibration (Online)



# Experimental Results

- Online Calibration



# Experimental Results

## Online Calibration

### Amplitude

Measurement Step	Max	Min	Mean	Std. Dev.
Initial (Uncalib.)	6.238	0.096	1.248	1.046
2nd Reading	1.026	0.997	1.000	0.003
3rd Reading	1.092	0.614	0.994	0.046

## Offline Calibration

Measurement Step	Max	Min	Mean	Std. Dev.
Initial (Uncalib.)	3.518	0.085	1.099	0.700
Calibrated Data 2	1.238	0.774	0.989	0.067
Calibrated Data 3	1.223	0.826	0.991	0.070

### Phase

Measurement Step	Max	Min	Mean	Std. Dev.
Initial (Uncalib.)	173.59	-179.34	-36.15	74.32
2nd Reading	0.33	-0.32	0.00	0.06
3rd Reading	3.12	-7.47	0.01	0.83

Measurement Step	Max	Min	Mean	Std. Dev.
Initial (Uncalib.)	179.50	-178.97	-22.24	76.54
Calibrated Data 2	12.25	-13.99	-0.13	4.06
Calibrated Data 3	11.22	-11.26	-0.81	4.01

# Conclusion

Conventional offline calibration methods are insufficient for wideband SDRs ,like ADALM-PLUTO, that require frequency agility over a 1 GHz bandwidth.

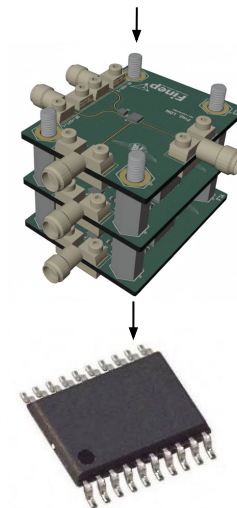
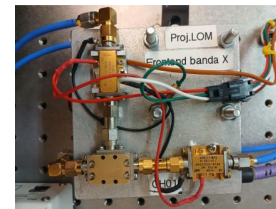
**Proposed Solution:** A real-time, "in-place" calibration methodology was successfully implemented to overcome the limitations of traditional approaches.

**Validation:** The technique effectively corrected significant gain and phase imbalances across various frequencies, proving its suitability for frequency-agile systems.

## Future Work:

- Miniaturize the hardware to fit a 1U CubeSat standard.
- Integrate additional antennas to evaluate Angle of Arrival (AoA) estimation performance.

Miniaturize the circuit



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**Thanks for your attention!**  
**Obrigado!**

**Any Questions?**

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