

# FT2025

SWEDISH AEROSPACE  AT THE CROSSROADS

The 12th Swedish  
Aerospace Technology Congress  
FT2025 in Stockholm  
October 14-15, 2025

## ROBUST PRIORITY ASSIGNMENT APPLIED TO AVIONICS FULL-DUPLEX SWITCHED ETHERNET NETWORKS

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## OUTLINE

- Introduction
- Background and Problem Statement
- AFDX Network
- OPA and RPA scheduling
- Experimental and Results
- Conclusion

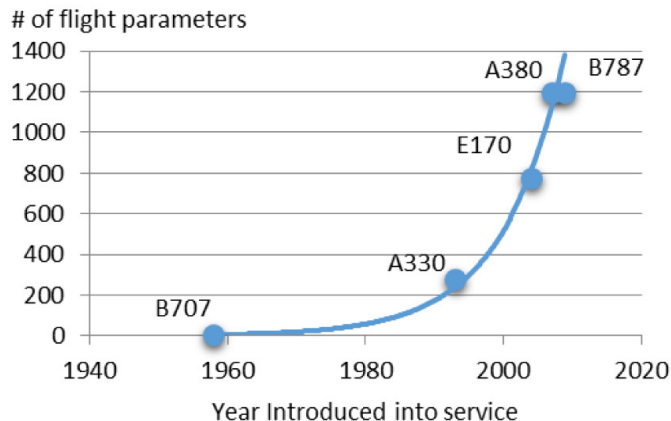
A blurred, high-angle view of an aircraft cockpit. The image shows various instruments, control panels, and displays, including a large central display showing a map or terrain, and several smaller displays on the left and right sides. The cockpit is filled with numerous buttons, knobs, and switches, all rendered in a soft, out-of-focus manner. The overall color palette is dominated by light blues and greys, giving it a clean, modern feel.

# INTRODUCTION

## INTRODUCTION

- Increasing complexity of modern avionics networks

Evolution of FDR data capacity



- From tens to thousands flight parameters to handle
- Number of networked devices embedded in an aircraft followed the same growth pace

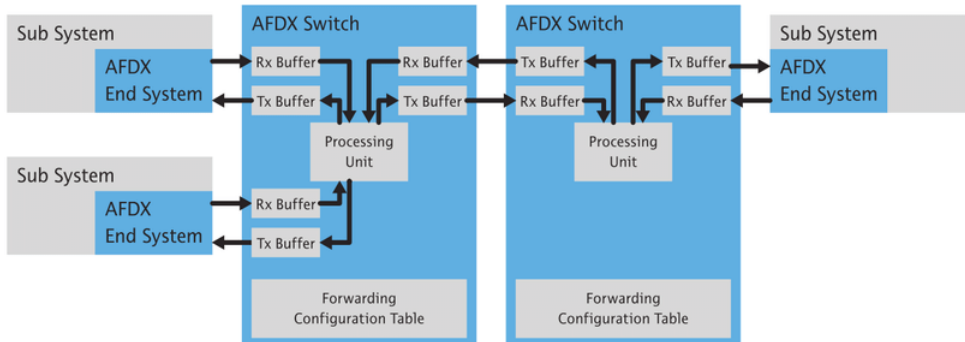
## INTRODUCTION

- These devices need deterministic and fault-tolerant data communication
- ARINC 429 limits scalability and efficiency
- ARINC 664 (AFDX) provides Ethernet-based multiplexing communication solution



## INTRODUCTION

- Despite system-level deterministic, AFDX networks as the communication backbone introduces **indeterminism at the switch level**



- Switch processing delay variability (**jitter**)
- Output port contention
- Challenge:** ensure bounded end-to-end delays in variable conditions

## INTRODUCTION – GOAL AND CONTRIBUTION

- Study a Priority Assignment alternative that can handle the problem
- **Contribution:**
  - Proposal of integrating Robust Priority Assignment (RPA) into AFDX architecture
  - Comparative evaluation with Optimal Priority Assignment (OPA)



# Background and Problem Statement

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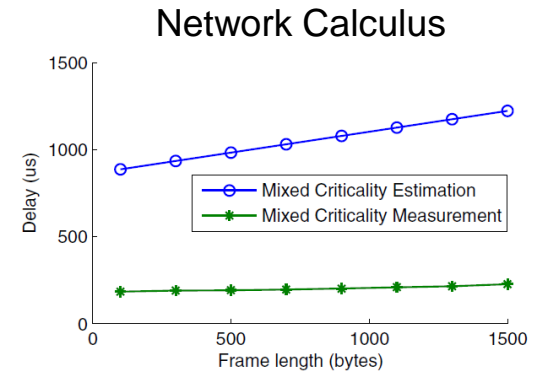
## BACKGROUND

- It is mandatory to provide an **upper bound for the end-to-end delay** of a given frame carrying flight-critical data between end systems
- Different approaches were developed to perform the schedulability analysis and calculate the worst-case delay for AFDX



## BACKGROUND

- Network Calculus, the first, is **too pessimist**, leading to **underutilization of the network**
- Trajectory Approach (TA) was applied with better results compared to Network Calculus – less pessimistic, **closer to the experimental results**



Yao et al, 2016

## BACKGROUND

- Increased number of data → priority assignment is essential
  - Avoid hardware underutilization
  - Allow scalability
- First In First Out (FIFO) mostly used
- Optimal Priority Assignment (OPA) was proposed to AFDX
  - It is mathematically optimal, but fragile

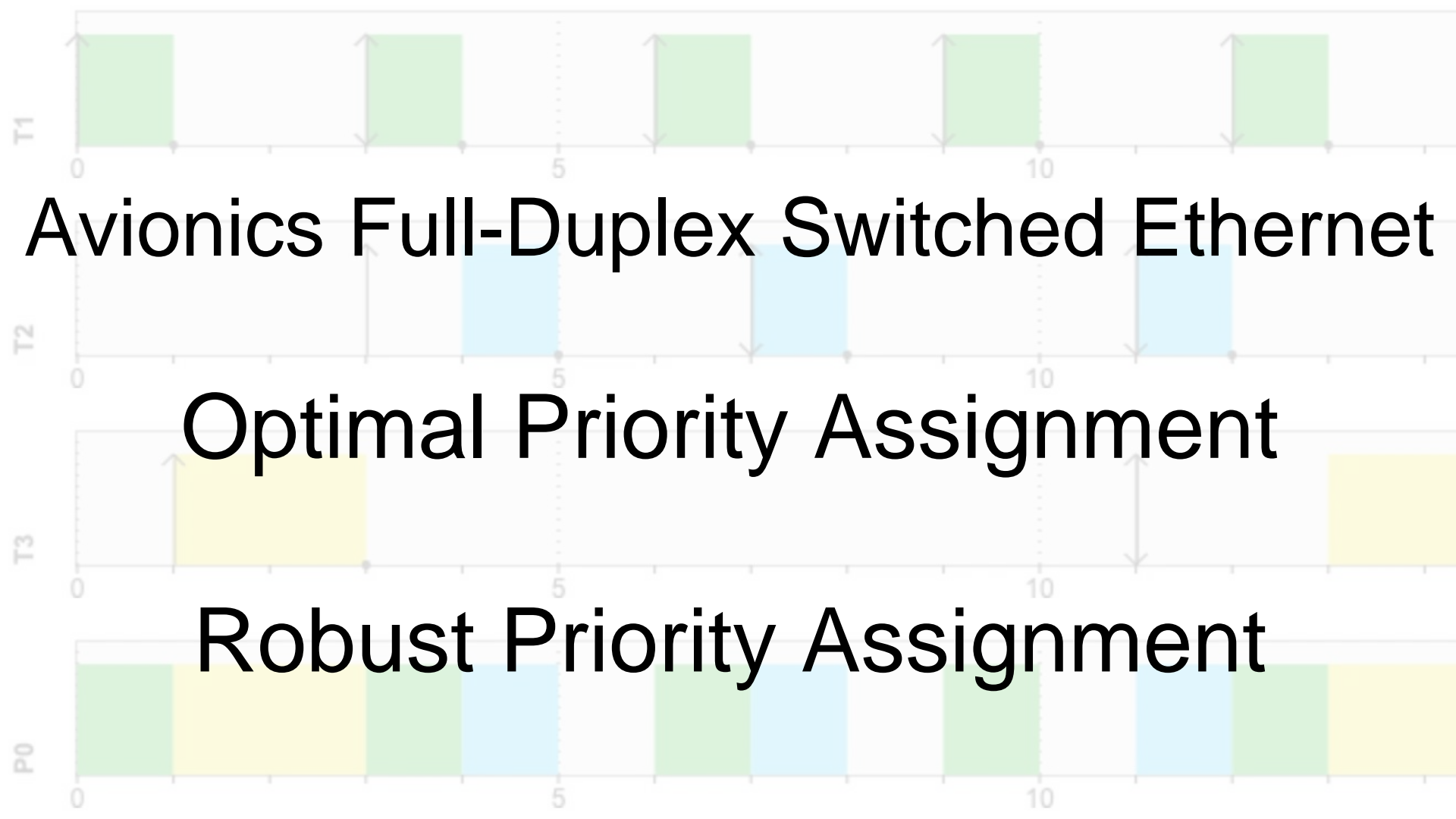
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## PROBLEM STATEMENT

- How to improve the AFDX determinism with priority assignment?
- An alternative is the use of Robust Priority Assignment (RPA)
  - Based on OPA
  - Stable under uncertainty



Avionics Full-Duplex Switched Ethernet

Optimal Priority Assignment

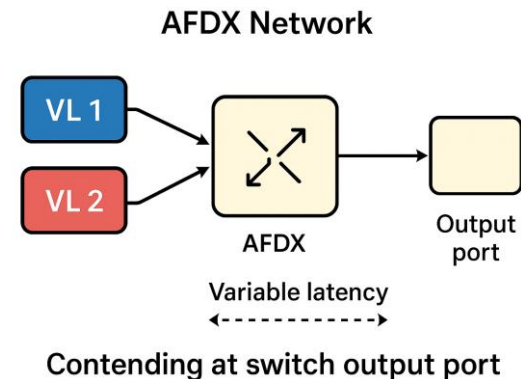
Robust Priority Assignment

# AVIONICS FULL-DUPLEX SWITCHED ETHERNET - AFDX

- Described in ARINC 664 Part 7 (deterministic Ethernet)
- Backbone of modern fly-by-wire systems
- It defines two priority levels
- It achieves determinism mainly through
  - **Virtual Links (VLs)**: predefined logical connections with guaranteed bandwidth
  - **Bandwidth Allocation Gap (BAG)**: ensures traffic shaping
  - **Redundancy**: dual networks for reliability

# AVIONICS FULL-DUPLEX SWITCHED ETHERNET - AFDX

- **System level determinism**, but the **switches** are store-and-forward devices that can **introduce indeterminism**
  - Each received frame is processed and forwarded in a **non-constant time**
  - Frames that must be forwarded to the same port are placed in a queue
  - The frame order is preserved per VL, but the queuing time depends on how many frames are waiting
  - Result: **jitter**



## OPTIMAL PRIORITY ASSIGNMENT - OPA

- Guarantees optimal ordering when feasible
- Based on exhaustive schedulability tests
- Minimizes worst-case response times
- But it is sensitive to evaluation order and **robustness is not addressed**
- Applied to AFDX
  - OPA does not specify the order of frames in each of the two AFDX priority levels
  - An unfavorable initial ordering may negatively impact the forwarding

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## ROBUST PRIORITY ASSIGNMENT - RPA

- Introduces interference tolerance model (errors, interrupts, etc...)
- Generates stable priority orders under timing variations
- Improves resilience to parameter and load fluctuations
- Increases feasibility margin in critical networks
- Suitable for mixed-criticality environments

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## RPA TO AFDX

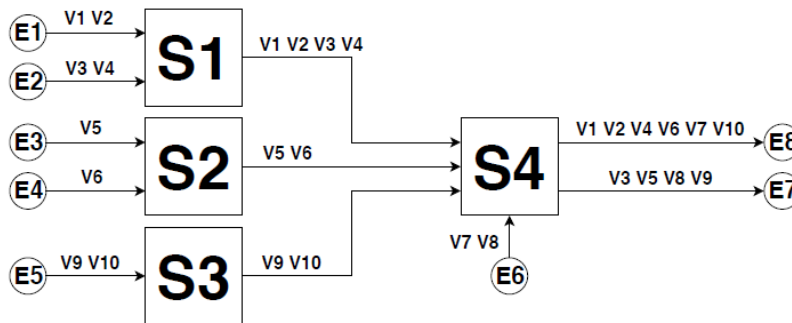
- Use of the two priority levels per switch allowed by AFDX
- RPA groups flows into tolerance classes
- With the improved ordering, it doesn't incur in the OPA's problem
- Enables practical implementation on avionics switches
- It can minimize the indeterminism in AFDX related to the switches

A surrealist background illustration featuring melting pocket watches, a face with a melting mouth, and a distorted landscape. The scene is rendered in a soft, painterly style with a muted color palette of blues, oranges, and greys. The text 'Experiments and Results' is centered over the image in a bold, black, sans-serif font.

# Experiments and Results

## COMPARATIVE ANALYSIS

- OPA and RPA priority ordering is done over 10 VLs (VL1–VL10)
- Worst-case end-to-end delay (WCETED) of all VLs calculated with Trajectory Approach for both



## COMPARATIVE ANALYSIS - PARAMETERS

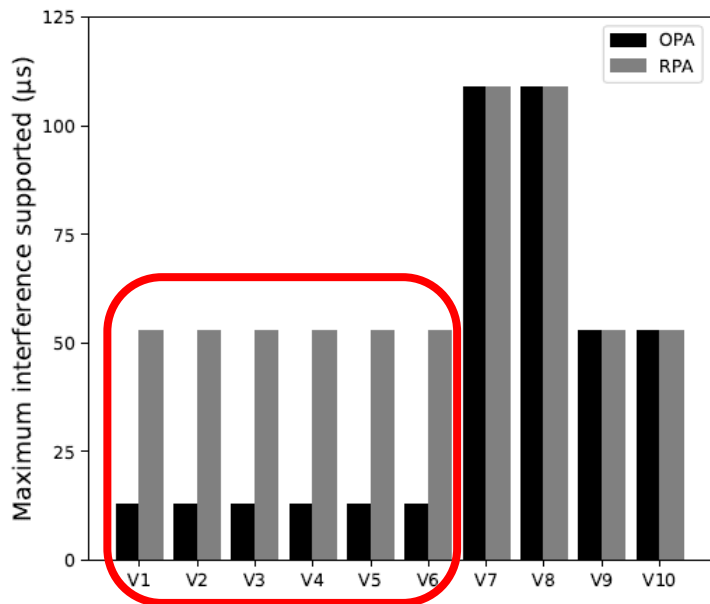
- BAG: 4000  $\mu$ s, Frame size: 4000 bits
- Deadline (D): 325  $\mu$ s (strict constraint)
- Simulates critical flight-control traffic patterns
- Metrics: delay and interference tolerance
- Interference Tolerance:  $D - WCETED$ 
  - “Spare time” before missing the deadline
  - Any additional interference up to this amount still maintains schedulability

## ASSIGNED PRIORITIES AND WCETED

*Priority assignment and WCETED of OPA and RPA.*

Virtual Link	Priority (OPA)	Priority (RPA)	WCETED (OPA) ( $\mu$ s)	WCETED (RPA) ( $\mu$ s)
V1	LOW	HIGH	312	272
V2	LOW	HIGH	312	272
V3	LOW	HIGH	312	272
V4	LOW	HIGH	312	272
V5	LOW	HIGH	312	272
V6	LOW	HIGH	312	272
V7	LOW	LOW	216	216
V8	LOW	LOW	216	216
V9	LOW	LOW	272	272
V10	LOW	LOW	272	272

## MAXIMUM INTERFERENCE SUPPORTED



- RPA achieved a +40µs robustness gain in V1-V6

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## STRESSING THE SYSTEM

- Deadlines of two VLs (VL1 and VL6) were decreased from 325 to 300 to stress the system
- Force the change in the VLs prioritization
- All the remaining parameters continue the same, as well as the topology

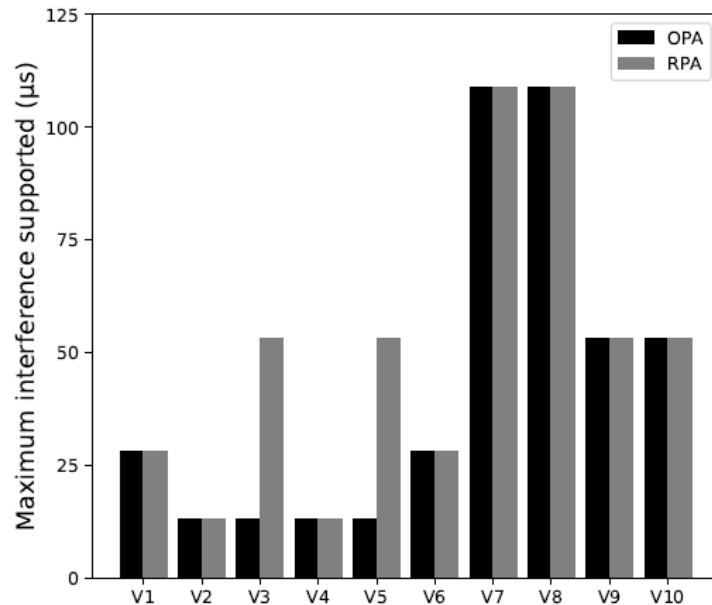
## ASSIGNED PRIORITIES AND WCETED – STRESSED SYSTEM

*Priority assignment and WCETED of OPA and RPA after decreasing deadlines of V1 and V6.*

Virtual Link	Priority (OPA)	Priority (RPA)	WCETED (OPA) (μs)	WCETED (RPA) (μs)
V1	HIGH	HIGH	272	272
V2	LOW	LOW	312	312
V3	LOW	HIGH	312	272
V4	LOW	LOW	312	312
V5	LOW	HIGH	312	272
V6	HIGH	HIGH	272	272
V7	LOW	LOW	216	216
V8	LOW	LOW	216	216
V9	LOW	LOW	272	272
V10	LOW	LOW	272	272

- OPA changes the prioritization of V1 and V6
- RPA changes the prioritization of V2 and V4

## MAXIMUM INTERFERENCE SUPPORTED – STRESSED SYSTEM



The gains provided by RPA diminish, only V3 and V5 present increased interference support

## LESSONS LEARNED AND PROPOSAL

- The most robust priority assignment was achieved with RPA
- But the overall robustness of the system could not be increased
- RPA is a viable strategy
  - To enhance robustness: parameters of the network must be analyzed
- **Proposal: Robustness Booster Module**
  - Make redistributions of the slack time according to priority promotions
  - AI methods can be explored for this

A grayscale photograph of an airplane cockpit, viewed from the pilot's perspective. The cockpit is filled with various instruments, including a primary flight display (PFD) on the left, a multi-function display (MFD) in the center, and another PFD on the right. The instrument panel is densely packed with buttons, knobs, and gauges. The word "Conclusion" is overlaid in a large, bold, black font in the center of the image. The background shows a runway at night, illuminated by lights, with a city skyline visible in the distance.

# Conclusion

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## CONCLUSION

- RPA enhances AFDX robustness and delay tolerance
- Significant gains were reported in the provided robustness (supported interference)
- The use of RPA complies with certifiable robust scheduling
- The approach can be used as a foundation for the future proposed Robustness Booster Module exploring AI-based methods

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## THANK YOU!

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## BACKUP SLIDES